

## **KLEP and KPLO**



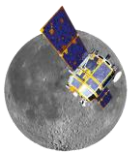
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**Lunar Exploration Program Office**  
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# **Introduction to Korea Lunar Exploration Program and KPLO Mission**

**August, 2016**

**Korea Aerospace Research Institute**

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# KLEP (Korea Lunar Exploration Program) Overview

## 1<sup>st</sup> Phase: Korea Pathfinder Lunar Orbiter Mission

- Technology demonstration for lunar missions
- Lunar sciences
- New technology demonstration (DTN)
- International cooperation
- Use foreign launch service



**Payloads  
[1<sup>st</sup> Phase]**

- Lunar science payloads
- International payloads
- Space internet (DTN)



**Preliminary  
Study**

- Lunar rover technology
- Energy technology(RTG)
- Launch vehicle upper stage technology
- Lunar landing technology



**Ground Station**

- Deep-space antenna
- Tracking and navigation
- Science/Imaging data processing
- TM & TC Operation

## 2<sup>nd</sup> Phase: Lunar Orbiter and Lander Mission

- Lunar orbiter, lander mission
- Lunar lander includes a rover
- Use Korean launch vehicle



**Lunar  
Orbiter**



**Lunar  
Lander**



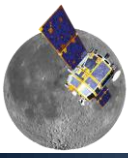
**Payloads  
[2<sup>nd</sup> Phase]**

- Lunar Resources
- Topography
- Space Environment



**LV  
Upper stage**

- TLI insertion
- 550kg to TLI



# KPLO(Korea Pathfinder Lunar Orbiter) Mission Overview

## Program Overview

Goal Enhancement of the lunar exploration technology and science research

Orbit	Polar orbit 100km
Mass	550kg
Mission lifetime	1 year

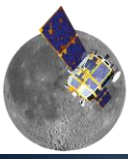
Target Launch date	End of 2018
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## Main Contents

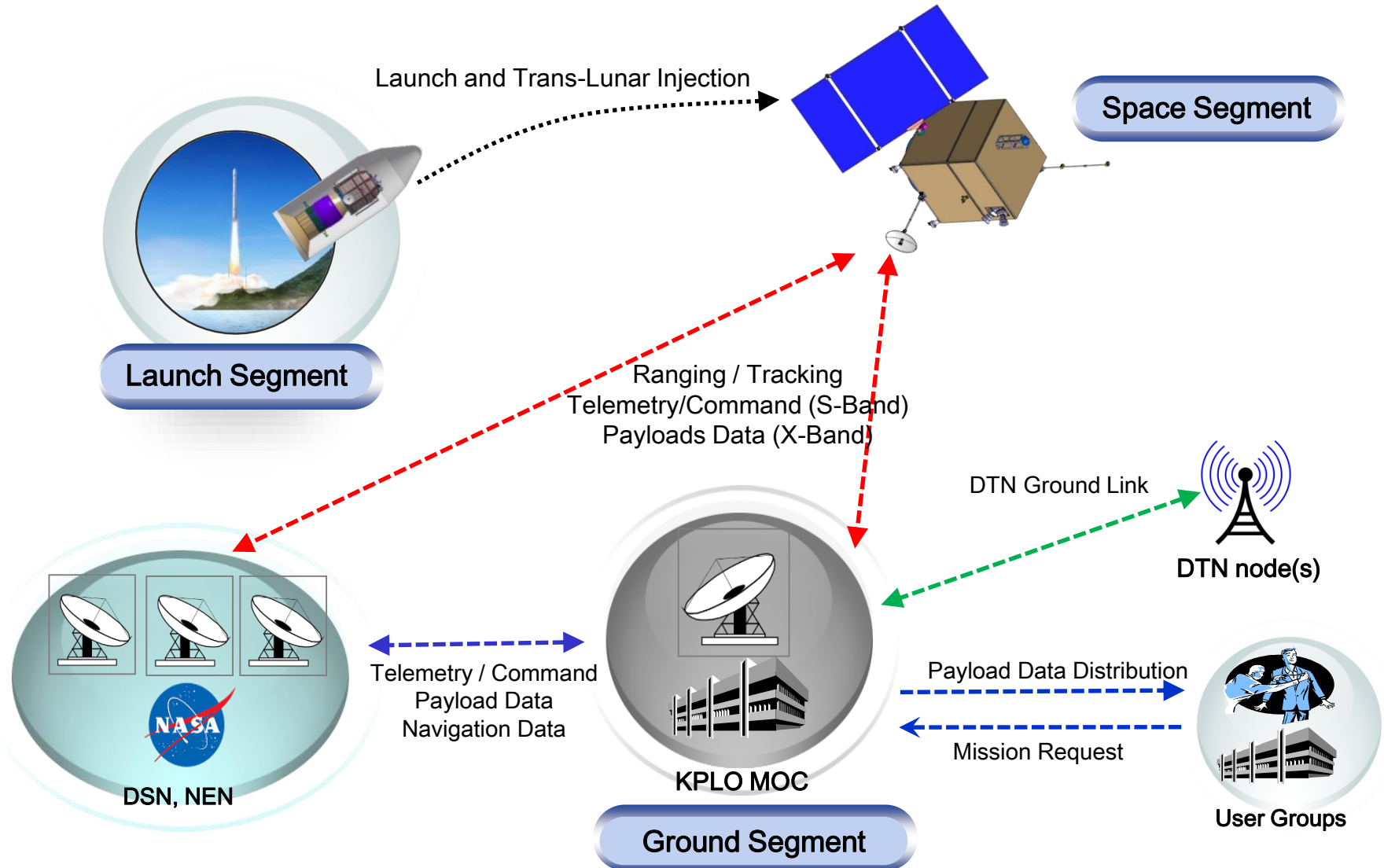
- System and Bus development
- Building a Ground-station for deep space mission
- Scientific instruments (Domestic/International)
- Space internet demonstration

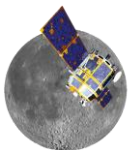
## KPLO Mission Objectives

1. Developing indigenous lunar exploration technologies
  - Developing lunar exploration technologies (orbiter bus, lunar orbit insertion, operation, tracking, communication, navigation)
  - Building DSN Ground-station
2. Scientific investigation
  - Lunar topography
  - Scientific investigation on lunar environment and resources
3. Realizing space new technologies
  - Demonstration Space internet

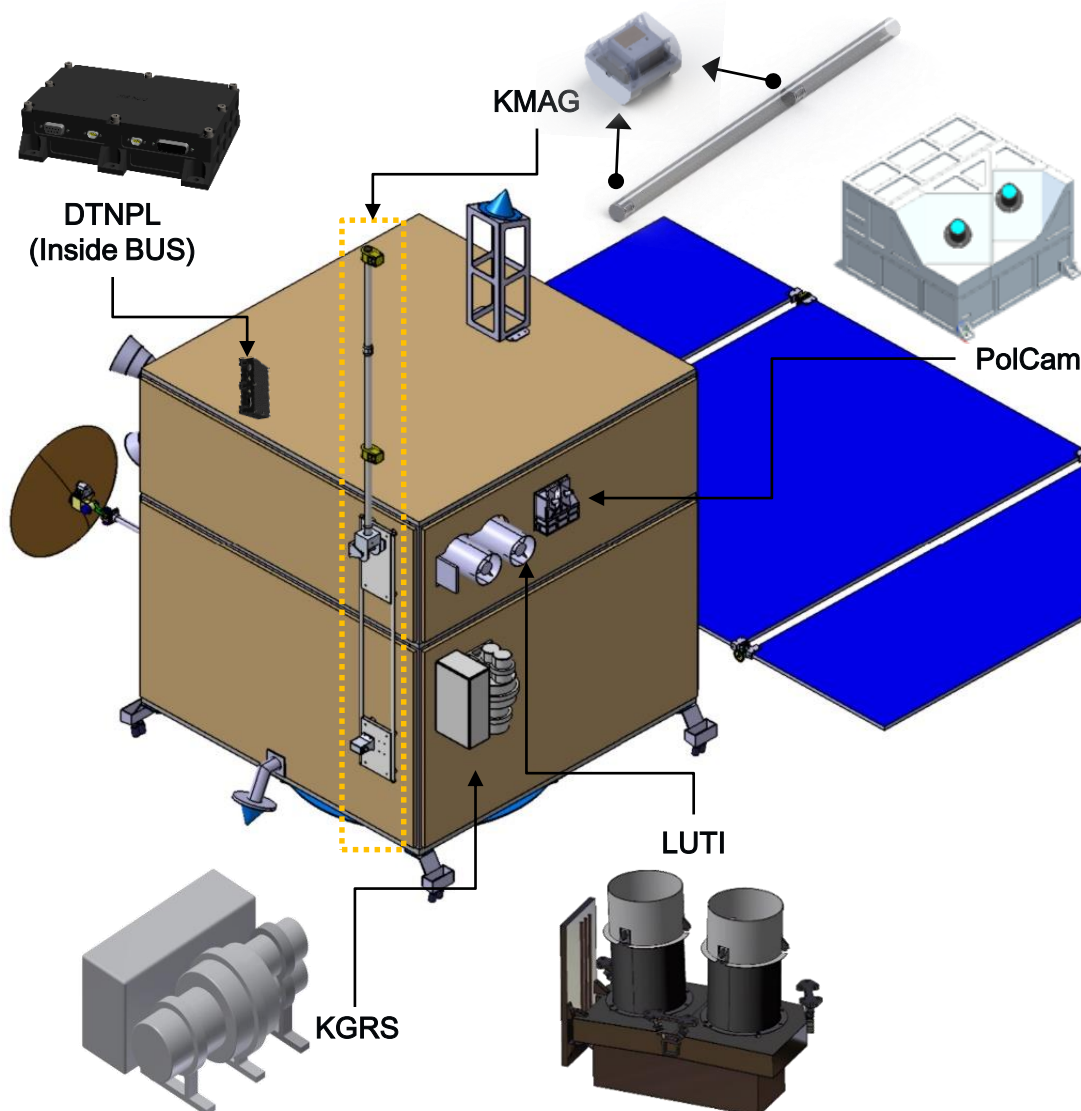


# Top Level System Architecture



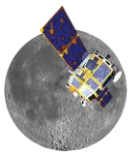


# KPLO Instruments Summary

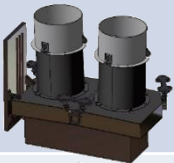
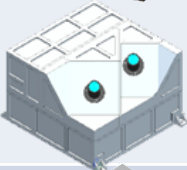
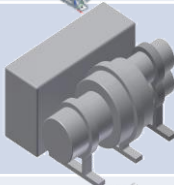
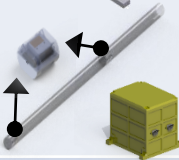



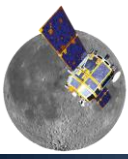
- **Lunar Terrain Imager (LUTI)** – LUTI will take images of probable landing sites for the 2<sup>nd</sup> stage lunar exploration mission and special target sites of the lunar surfaces with a high spatial resolution (<5m)
- **Wide-Angle Polarimetric Camera (PolCam)** – PolCam will acquire the polarimetric images of the entire lunar surface except for the polar regions with medium spatial resolution in order to investigate the detailed characteristics of lunar regolith.
- **KPLO Magnetometer (K MAG)** – K MAG will measure the magnetic strength of the lunar environment (up to ~100km above the lunar surface) with ultra-sensitive magnetic sensors.
- **KPLO Gamma Ray Spectrometer (KGRS)** – KGRS will investigate the characteristics of lunar resources including rare elements, minerals, etc., and map the spatial distribution of the elements.
- **Disruption Tolerant Network experiment payload (DTNPL)** – DTNPL will take space communication experiment based on disruption tolerant network technology.
- **NASA Provided Instrument(s)** will be selected through NASA/AO process.





# Korean Domestic Instruments

Instrument	Measurement	Exploration Benefit	Science Benefit
<b>LUTI (KARI+)</b> 	<5m resol images of selected regions of lunar surface	Future landing site for the next lunar mission	Geology, Topology of the lunar surface
<b>PolCam (KASI+)</b> 	First polarimetric map of near-/far-side of the moon	Effect of lunar soil on electro-mechanical parts of landing module	Characteristics of lunar regolith, Space weathering process
<b>KGRS (KIGAM+)</b> 	Map of major elements (Mg, Ni, Cr, Ca, Al, Ti, Fe, Si, O, U, He-3, Water)	Better knowledge of space environments; Radiation environment for manned mission	Distribution of lunar resources; Water/mineral contents
<b>KMAG (KHU+)</b> 	3D map of lunar magnetism, magnetic information of lunar swirls	Better knowledge of space environments	Origin of the Moon, Lunar magnetic evolution
<b>DTNPL (ETRI+)</b> 	Technical demonstration payload for experimental testing of Disruption Tolerant Network technology in space	Effective communications in delay / disruptive condition in deep space exploration	N/A



# Instrument-Directed Science Goals

## □ LUTI

- Obtain high-resolution images of future landing sites (2<sup>nd</sup> stage Korean Lunar Exploration Mission)
- Target observation of interesting places on the Moon

## □ PolCam

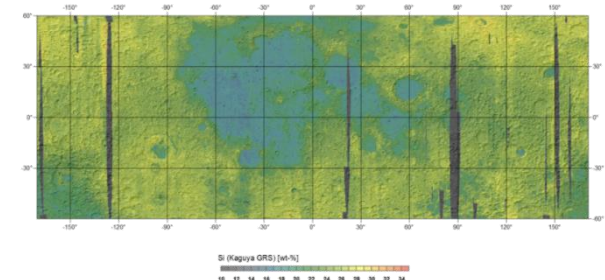
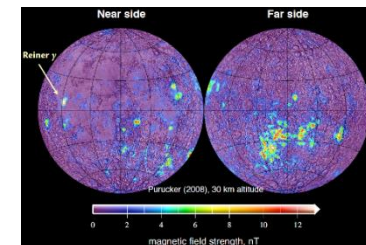
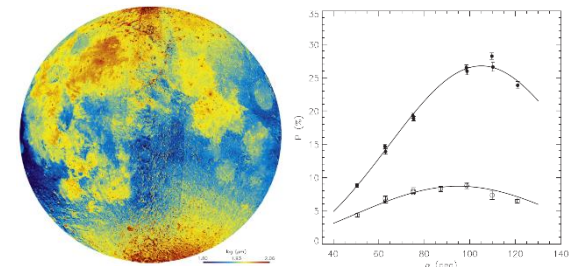
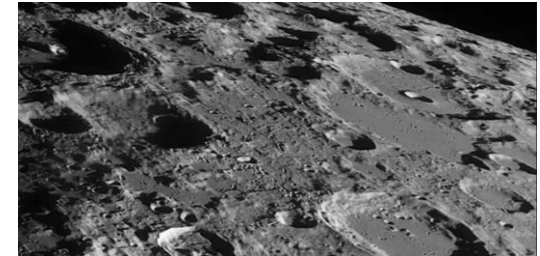
- Polarimetric imaging survey of the entire lunar surface except for the pole regions at various phase angles ( $0^\circ \sim 120^\circ$ ) and spectral bands (320, 430, 650nm)
- Investigate the characteristics of lunar regolith and Ti contents (varying latitude, longitude, mare & high-lands)

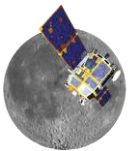
## □ KMAG

- Investigate the origin of the crustal magnetism of the Moon (Impact/Dynamo, etc.)
- Characteristics of the lunar magnetic anomalies

## □ KGRS

- Map the distribution of major elements on the lunar surface and the beneath of the surface (up to 50cm)
- Geological and geochemical activities of the Moon
- Obtain radiation map of lunar environment





# Ground Segment

## Goal

- Establish Korea DSN Antenna(26~34m) compatible with Worldwide DSN in Korea
- Implement an Operational Ground Station for TC/TM & Science Data Processing

## Payload Data Processing

- Multi-Payloads Data Storage & Pre-Processing
- Science & Image Data Processing & Management
- Payloads Data Calibration & Validation

## DSN

- Multi-band Large Antenna Design
- Ranging for Moon & Deep Space
- Protocol Design compatible with NASA DSN/ESA ESTRACK
- Modulation/Demodulation & Coding for Deep Space

## Mission Planning

- Mission Req. Collection & Scheduling
- Mission Conflict Detection & Re-Scheduling
- Orbiter/Lander Timeline Generation & Distribution

## Simulator

- Orbiter/Lander Simulation

## Spacecraft Control

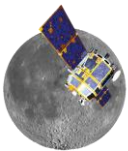
- CCSDS
- Telemetry Data Real-time Processing
- Telecommand Generation & Processing

## Flight Dynamics & Navigation

- Tracking Data Processing
- Orbit Determination & Prediction
- Orbit Maneuver(TLI, MCC & LOI)
- Sensor Calibration







**Thank you**

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